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willy@17-04-2014-MEDI MINGW64 ~  
$ cd Documents/GitHub/ardupilot
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willy@17-04-2014-MEDI MINGW64 ~/Documents/GitHub/ardupilot (MisRelDec_PlayCopy)  
$ git submodule update --init --recursive  
Submodule path 'modules/ChibiOS': checked out '331fe75d4848698b5d2e521e7cd9e95a3595688b'  
Submodule path 'modules/gbenchmark': checked out  
'8039b4030795b1c9b8cedb78e3a2a6fb89574b6e'  
Submodule path 'modules/gtest': checked out '10b1902d893ea8cc43c69541d70868f91af3646b'  
Submodule path 'modules/libcanard': checked out  
'99163fc2369e5e5f75f8473f0b950b3418830d3f'  
Submodule path 'modules/libcanard/drivers/avr/avr-can-lib': checked out  
'9c6bc9118de66d6edaf1b8539e2b9717ba26d123'  
Submodule path 'modules/libcanard/dsd1_compiler/pyuavcan': checked out  
'7a149d6b106cf6ec6c170acf93f5bfd1ce88d779'  
Submodule path 'modules/libcanard/dsd1_compiler/pyuavcan/uavcan/dsd1_files': checked out  
'103745afb42f15f83d49fc23530f7fe2c11358b8'  
Submodule path 'modules/mavlink': checked out 'd8cad47bb3e4ecf21ae631e492e9643cd063cb8c'  
Submodule path 'modules/mavlink/pymavlink': checked out  
'1a6faa8b97950158682b932c1444d4488df4adcd'  
Submodule path 'modules/uavcan': checked out '3ef4b88d96466bbcf886f74d0ae169a4c8c1bdb0'  
Submodule path 'modules/uavcan/dsd1': checked out  
'192295c4f9b67f4a20b0eabf74757b6597415f2b'  
Submodule path 'modules/uavcan/libuavcan/dsd1_compiler/pyuavcan': checked out  
'c58477a644d20ccf95a20c151f3a0402f271c3b8'  
Submodule path 'modules/uavcan/libuavcan/dsd1_compiler/pyuavcan/dsd1': checked out  
'fd12483ddd4e58242d61d74a163e7aeaa1e0f466'  
Submodule path 'modules/waf': checked out '67b3eac550520cd8a7cd1dce0f77820e91fb8ad0'
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willy@17-04-2014-MEDI MINGW64 ~/Documents/GitHub/ardupilot (MisRelDec_PlayCopy)  
$ git fetch upstream  
remote: Enumerating objects: 81, done.  
remote: Counting objects: 100% (81/81), done.  
remote: Compressing objects: 100% (9/9), done.  
remote: Total 102 (delta 73), reused 74 (delta 72), pack-reused 21  
Receiving objects: 100% (102/102), 25.18 KiB | 1.32 MiB/s, done.  
Resolving deltas: 100% (74/74), completed with 39 local objects.  
From https://github.com/ArduPilot/ardupilot  
8e34388a20..4a7f663cad master -> upstream/master
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willy@17-04-2014-MEDI MINGW64 ~/Documents/GitHub/ardupilot (MisRelDec_PlayCopy)  
$ git rebase upstream/master  
First, rewinding head to replay your work on top of it...  
Applying: AP_HAL: add AP_Mission_Relative support.  
Applying: AP_Mission: add AP_Mission_Relative support.  
Applying: Copter: add AP_Mission_Relative support.  
Applying: Plane: add AP_Mission_Relative support  
Applying: Sub: add AP_Mission_Relative support  
Applying: Rover: add AP_Mission_Relative support  
Applying: Tools: add MSGH and SKD locations  
Using index info to reconstruct a base tree...  
M Tools/autotest/locations.txt  
M modules/mavlink  
Falling back to patching base and 3-way merge...  
Failed to merge submodule modules/mavlink (commits don't follow merge-base)  
Auto-merging modules/mavlink  
CONFLICT (submodule): Merge conflict in modules/mavlink  
Auto-merging Tools/autotest/locations.txt  
CONFLICT (content): Merge conflict in Tools/autotest/locations.txt  
error: Failed to merge in the changes.  
hint: Use 'git am --show-current-patch' to see the failed patch  
Patch failed at 0007 Tools: add MSGH and SKD locations  
Resolve all conflicts manually, mark them as resolved with  
"git add/rm <conflicted_files>", then run "git rebase --continue".  
You can instead skip this commit: run "git rebase --skip".  
To abort and get back to the state before "git rebase", run "git rebase --abort".
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willy@17-04-2014-MEDI MINGW64 ~/Documents/GitHub/ardupilot (MisRelDec_PlayCopy|REBASE  
7/10)  
$ git rebase --abort
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willy@17-04-2014-MEDI MINGW64 ~/Documents/GitHub/ardupilot (MisRelDec_PlayCopy)  
$
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