

# PARAMETERS

## I/O Mapping

ArduPilot						
PWM	S1	PB0	5 V tolerant I/O	PWM1 GPIO50	TIM8_CH2N	Group1
	S2	PB1	3.3 V tolerant I/O	PWM2 GPIO51	TIM8_CH3N	
	S3	PA0	5 V tolerant I/O	PWM3 GPIO52	TIM5_CH1	
	S4	PA1	5 V tolerant I/O	PWM4 GPIO53	TIM5_CH2	Group2
	S5	PA2	5 V tolerant I/O	PWM5 GPIO54	TIM5_CH3	
	S6	PA3	5 V tolerant I/O	PWM6 GPIO55	TIM5_CH4	
	S7	PD12	5 V tolerant I/O	PWM7 GPIO56	TIM4_CH1	Group3
	S8	PD13	5 V tolerant I/O	PWM8 GPIO57	TIM4_CH2	
	S9	PD14	5 V tolerant I/O	PWM9 GPIO58	TIM4_CH3	
	S10	PD15	5 V tolerant I/O	PWM10 GPIO59	TIM4_CH4	Group4
	S11	PE5	5 V tolerant I/O	PWM11 GPIO60	TIM15_CH1	
	S12	PE6	5 V tolerant I/O	PWM12 GPIO61	TIM15_CH2	
LED	PA8	5 V tolerant I/O	PWM13 GPIO62	TIM1_CH1	Group5	
				SERVO13_FUNCTION 120, NTF_LED_TYPES neopixel		

PWM1~PWM13 are Dshot and PWM capable. However, mixing Dshot and normal PWM operation for outputs is restricted into groups, ie. enabling Dshot for an output in a group requires that ALL outputs in that group be configured and used as Dshot, rather than PWM outputs.  
If servo and motor are mixed in same group, make sure this group run lowest PWM frequency according to the servo specification, ie. Servo supports Max. 50Hz, ESC must run at 50Hz in this group.

ADC	Vbat pad 1K:10K divider builtin	PC0	0-36V	Vbat ADC onboard battery voltage sense	BATT_VOLT_PIN BATT_VOLT_MULT	10 11.0
	Curr pad	PC1	0-3.3V	Current ADC onboard current sense	BATT_CURR_PIN BATT_AMP_PERVLT	11 66.7
	VB2 Pad 1K:20K divider builtin	PA4	0-69V	Vbat2 ADC	BATT2_VOLT_PIN BATT2_VOLT_MULT	18 21.0
	CU2 Pad	PA7	0-3.3V	Current2 ADC	BATT2_CURR_PIN BATT2_AMP_PERVLT	7 /
	RSSI Pad	PC5	0-3.3V	RSSI ADC Analog RSSI	RSSI_ANA_PIN RSSI_TYPE	8 1
	AirS Pad 20K:20K divider builtin	PC4	0-6.6V	AirS ADC Analog Airspeed	ARSPD_PIN ARSPD_TYPE	4 2
I2C	I2C1 CL1/DA1	PB6/PB7	5 V tolerant I/O	Compass	COMPASS_AUTODEC	1
	I2C2 CL2/DA2 on JST-GH-4P	PB10/PB11	5 V tolerant I/O	on board Baro DPS310	Address	0x76
				Digital Airspeed I2C MS4525 DLVR-L10D	ARSPD_BUS ARSPD_TYPE ARSPD_TYPE	0 1 9
CAN	CAN1	PD0/PD1	5 V tolerant I/O	CAN Node	CAN_D1_PROTOCOL CAN_P1_DRIVER	1 1
				CAN GPS	GPS_TYPE	9
				CAN Compass	COMPASS_TYEMASK	0
				CAN Airspeed sensor	ARSPD_TYPE	8
UART	USB	PA11/PA12	5 V tolerant I/O	USB	console	SERIAL0
	RX7 TX7 RTS7 CTS7	PE7/8/9/10	3.3 V tolerant I/O	UART7	telem1	SERIAL1
	TX1 RX1	PA9/PA10	5 V tolerant I/O	USART1	telem2	SERIAL2
	TX2 RX2	PD5/PD6	5 V tolerant I/O	USART2	GPS1	SERIAL3
	TX3 RX3	PD8/PD9	5 V tolerant I/O	USART3	GPS2	SERIAL4
	TX8 RX8	PE1/PE0	5 V tolerant I/O	UART8	USER	SERIAL5
	TX4 RX4	PB9/PB8	5 V tolerant I/O	UART4	USER	SERIAL6
	TX6 RX6	PC6/PC7	5 V tolerant I/O	USART6	RC input/Receiver SBUS/BUS/DSM/PPM	SERIAL7

S1 → CONTROLLER WIRE 1  
S3 → CONTROLLER WIRE UNMARKED

→ TELEMETRY

→ CROSSFIRE

INAV					
PWM	S1	PB0	5 V tolerant I/O	TIM3_CH3	Fixed Wing Motor
	S2	PB1	3.3 V tolerant I/O	TIM3_CH4	
	S3	PA0	5 V tolerant I/O	TIM5_CH1	
	S4	PA1	5 V tolerant I/O	TIM5_CH2	Fixed Wing Servo
	S5	PA2	5 V tolerant I/O	TIM5_CH3	
	S6	PA3	5 V tolerant I/O	TIM5_CH4	
	S7	PD12	5 V tolerant I/O	TIM4_CH1	
	S8	PD13	5 V tolerant I/O	TIM4_CH2	
	S9	PD14	5 V tolerant I/O	TIM4_CH3	
	S10	PD15	5 V tolerant I/O	TIM4_CH4	
	S11	PE5	5 V tolerant I/O	TIM15_CH1	
	S12	PE6	5 V tolerant I/O	TIM15_CH2	
LED	PA8	5 V tolerant I/O	TIM1_CH1	2812LED	
ADC	Vbat pad 1K:10K divider builtin	PC0	0-36V	Vbat ADC ADC_CHANNEL_1	scale 1100
	Curr Pad	PC1	0-3.3V	Current ADC ADC_CHANNEL_2	scale 150
	RSSI Pad	PC5	0-3.3V	RSSI ADC ADC_CHANNEL_3	Analog RSSI
	AirS Pad 20K:20K divider builtin	PC4	0-6.6V	AirS ADC ADC_CHANNEL_4	Analog Airspeed
	VB2 Pad 1K:20K divider builtin	PA4	0-69V	ADC_CHANNEL_5	scale 2100
	CU2 Pad	PA7	0-3.3V	ADC_CHANNEL_6	spare
I2C	I2C1 CL1/DA1	PB6/PB7	5 V tolerant I/O	Compass	QMC5883 / HMC5883 IST8310 / IST8308 MAG3110 / LIS3MDL
				OLED	0.96"
	I2C2 CL2/DA2 on JST-GH-4P	PB10/PB11	5 V tolerant I/O	onboard Barometer	DPS310
				Digital Airspeed sensor	MS4525
UART	USB	PA11/PA12	5 V tolerant I/O	USB	
	TX1 RX1	PA9/PA10	5 V tolerant I/O	USART1	telem2
	TX2 RX2	PD5/PD6	5 V tolerant I/O	USART2	GPS1
	TX3 RX3	PD8/PD9	5 V tolerant I/O	USART3	GPS2
	TX4 RX4	PB9/PB8	5 V tolerant I/O	UART4	USER
	TX6 RX6	PC6/PC7	5 V tolerant I/O	TX6 & RX6	CRSF
	RX7 TX7	PE7/PE8	3.3 V tolerant I/O	UART6_RX	SBUS/BUS/DSM/PPM
	TX8 RX8	PE1/PE0	5 V tolerant I/O	UART8_TX	FPORT/SRX12

CHANNEL 3 CRSF TX  
CHANNEL 4 CRSF R.  
SERIAL7\_PROTOCOL = 2;  
RSSI\_TYPE = 3