

Analysis of aborted auto-landings 14sep18 at Rancho San Antonio. Radian Pro + Matek F405-Wing + ArduPlane latest Master / ChibiOS

Mission Planner 1.3.58.1 build 1.3.6823.9561

Distance: 0.7727 km
Prev: 554.66 m AZ: 257
Home: 556.81 m

Waypoints

WP Radius: 50 | Loiter Radius: 100 | Default Alt: 50 | Relative | Verify Height | Add Below | Alt Warn: 10

	Command	WP Radius	Loiter Radius	Default Alt	Relative	Verify Height	Lat	Long	Alt	Delete	Up	Down	Grad %	Angle	Dist	AZ
5	WAYPOINT	50	100	50	Relative	<input type="checkbox"/>	37.3312746	-122.0868158	100	X	🏠	🏠	22.8	12.9	89.9	167
6	WAYPOINT	50	100	50	Relative	<input type="checkbox"/>	37.3305922	-122.0862472	80	X	🏠	🏠	-22.0	-12.4	93.2	146
7	WAYPOINT	50	100	50	Relative	<input type="checkbox"/>	37.3300974	-122.0852816	60	X	🏠	🏠	-19.7	-11.1	103.5	123
8	DO_LAND_START	50	100	50	Relative	<input type="checkbox"/>	37.3300974	-122.0852816	60	X	🏠	🏠	0	0	0	0
9	WAYPOINT	50	100	50	Relative	<input type="checkbox"/>	37.3304898	-122.0842624	40	X	🏠	🏠	-20.0	-11.3	102.1	64
10	WAYPOINT	50	100	50	Relative	<input type="checkbox"/>	37.3310869	-122.084552	20	X	🏠	🏠	-28.1	-15.7	73.9	339
11	LAND	50	100	50	Relative	<input type="checkbox"/>	37.3315732	-122.0848846	0	X	🏠	🏠	-32.5	-18.0	64.7	331

10:10 AM
9/17/2018

Mission overview above