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sudo emacs /etc/default/arduplane
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```
TELEM1="-C /dev/ttyS1" TELEM2="-A udp:192.168.8.77:14550" #TELEM2="-C /dev/ttyAMA0" GPS="-B  
/dev/ttyS2"
```

```
# Options to pass to ArduPlane #ARDUPLANE_OPTS=$TELEM1 $TELEM2
```

```
# -A is a console switch (usually this is a Wi-Fi link) # -C is a telemetry switch # Usually this is either  
/dev/ttyAMA0 - UART connector on a Navio # or /dev/ttyUSB0 if you're using a serial to USB convertor
```

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# -B or -E is used to specify non default GPS
```

```
sudo emacs /lib/systemd/system/arduplane.service
```

```
[Unit] Description=ArduPlane Service After=networking.service Conflicts=arducopter.service  
ardupilot.service ardurover.service
```

```
[Service] EnvironmentFile=/etc/default/arduplane ExecStartPre=/bin/bash -c "/bin/echo uart >  
/sys/devices/platform/ocp/ocp:P9_21_pinmux/state" ExecStartPre=/bin/bash -c "/bin/echo uart >  
/sys/devices/platform/ocp/ocp:P9_22_pinmux/state" ExecStartPre=/bin/bash -c "/bin/echo uart >  
/sys/devices/platform/ocp/ocp:P9_24_pinmux/state" ExecStartPre=/bin/bash -c "/bin/echo uart >  
/sys/devices/platform/ocp/ocp:P9_26_pinmux/state" ExecStartPre=/bin/bash -c "/bin/echo  
pruecapin_pu > /sys/devices/platform/ocp/ocp:P8_15_pinmux/state"  
ExecStart=/usr/bin/ardupilot/blue-arduplane $TELEM1 $TELEM2 $GPS
```

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Restart=on-failure
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```
[Install] WantedBy=multi-user.target
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